

# BIOMECHANICS BASED MOTOR LEARNING

PHT PROJECT®

MODULO 1



A cura di Andrea Fusco

# MOTOR LEARNING

- Motor learning is a generic term comprising a huge diversity of phenomena
  - It can be applied to any movement made by human subjects in different tasks or activities

Consequently, It is of enormous practical relevance to several different fields:

- Sport
- Arts (Music, Dance, etc.)
  - Driving
- Rehabilitation

# Aim and Definition

- The essence of motor learning is producing more effective movements (improving motor skill, i.e. smoothness or accuracy of movements)
- Is a relatively permanent **change in behavior** resulting from experience and practice.
- Is **not directly observable**: its changes are inferred from performance changes.
- Is **necessary for complex movements** (such as speaking, playing piano, sports, etc.) but it is also important for
- **calibrating simple movements** (parameters of the body and environment change over time)

# AIM AND DEFINITION

- Rehabilitation is based on the **assumption that practice or training** leads to improvement of skills after neural damage
- Learning-related improvement is mediated by **changes in neural plasticity**
- Rehabilitation for patients with neurological disorders is fundamentally a process of **relearning how to move** in order to carry out their needs successfully

# AIM AND DEFINITION

Motor learning can be defined as  
any experience- dependent improvement in performance

- ✓ Movement goal selection
  - ✓ Action selection
  - ✓ Action execution

# MOTOR LEARNING AIMS

- improving skill
- maintaining consistent performance overtime  
in spite of
- Human changes: growth, fatigue, injury or damages
- Environmental changes

# MOTOR CONTROL DEFINITIONS

## 1. Skill acquisition

The ability to

- ✓ rapidly identify an appropriate movement goal in a particular task context
- ✓ select the correct action in relation to environmental stimuli and the current state of the body and
- ✓ execute that action with accuracy and precision

## 2. Skill maintenance

The ability to maintain performance levels of existing skills under changing conditions

# Learning Modalities

**Motor adaptation:** a particular type of behavioral change that involves adjusting how an already well-practiced action is executed to maintain performance in response to a change in the environment or the body

- Selecting an alternative well-practiced action
- Modifying how the current action is executed

i.e. **Sequence learning, *De novo* motor learning**



# Learning Modalities

- **Sequence learning**: learning the proper order of a sequence of discrete actions such that each is selected rapidly and executed accurately (i.e. goal selection and action selection).
- **De novo motor learning**: a new motor controller (some network or process that generates motor output) is developed



## Laboratory tasks

Discrete

**Sequence learning**  
(order of discrete actions)

**De Novo learning**  
(arbitrary discrete visuomotor associations)

Continuous

**Sequence learning**  
(continuous sequential actions)

**De Novo learning**  
(arbitrary continuous control)

**Adaptation**

**Motor acuity**

**Goal selection**

Choice of object or location that will require a movement / an effector

**Action selection**

Linking goal and stimuli to a particular movement

**Action execution**

Quality of movement

Being skilled in a motor task requires

From: *Krakauer et al. 2019*

# Learning (adaptation) components

A **first** component that:

- learns quickly
- is **poorly** retained
- is **explicit** and expressible only at ***high reaction times***
- is temporally ***labile***
- is driven by reward and task success

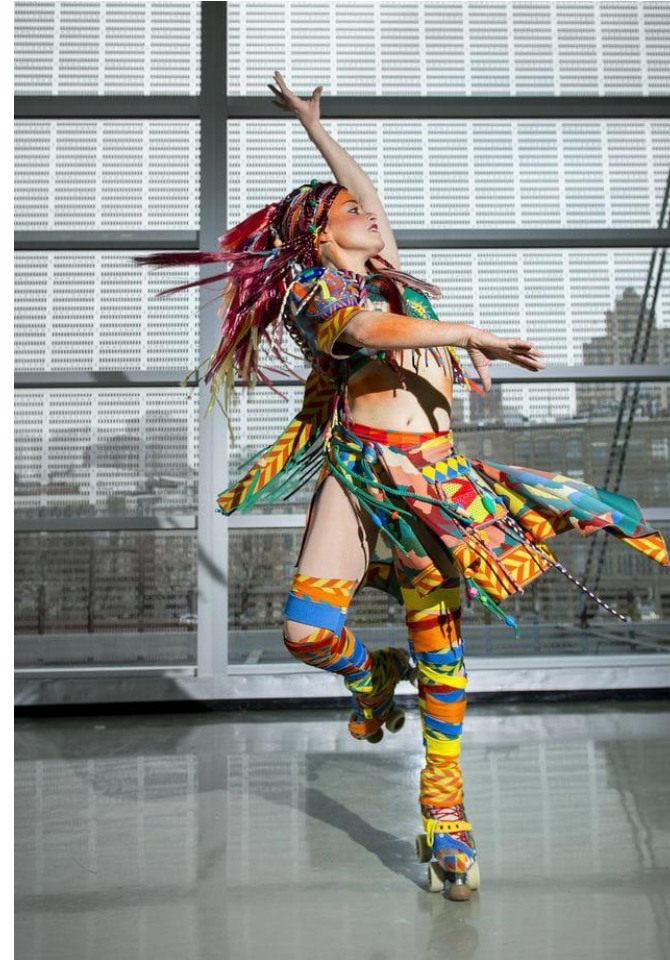
A **second** component that:

- learns slowly
- is retained **well**
- is **implicit** and expressible at ***low reaction times***
- is temporally ***stable***
- is driven by sensory prediction error

# Motor Adaptation

Capacity to compensate for environmental changes

- Visuo-spatial Rotations
- Force Perturbation



# Evidenze alla base del PHT\_Project

- il **muscolo** eroga maggiore forza quando in condizione di normotensione
- il **vantaggio meccanico** del sistema scheletrico è maggiore impiegando **coppie di forze** a partenza prossimale (momento vs. braccio)
- Il **controllo motorio** deve riguardare le azioni agonista e antagonista
- Il reclutamento nell'ambito delle catene cinetiche deve seguire la corretta **sequenza temporale e spaziale**

# BIBLIOGRAPHY

1. John W Krakauer, Alkis M Hadjiosif, Jing Xu , Aaron L Wong, Adrian M Haith, Motor Learning, Compr Physiol 2019 Mar 14;9(2):613-663.
2. Doyon J, Benali H, Current Reorganization and plasticity in the adult brain during learning of motor skills, Opinion in Neurobiology 2005, 15:161–167
3. Marinelli L, Quartarone A, Hallett M, Frazzitta G, Ghilardi MF, The many facets of motor learning and their relevance for Parkinson's disease Clinical Neurophysiology 128 (2017) 1127–1141
4. Basi scientifiche del Motor Learning e rilevanza per la riabilitazione, Lezioni del Prof. Giovanni Abbruzzese, DiNOGMI, University of Genoa (Italy), Scuola Specializzazione in Medicina Fisica e Riabilitativa